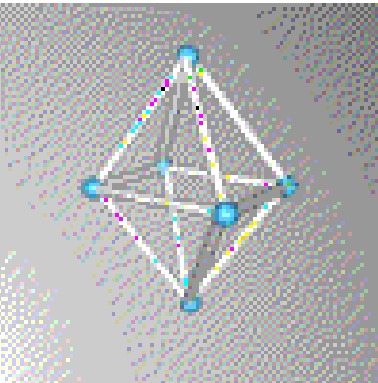


# Experiments in Sensor Network Applications: *Kansei Testbed*

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# Motivation for experimentation

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Our experience over the past five years in dealing with sensor network and their applications has been:

- progressive increase in scale :
  - from 10 → 100 → 10,000 nodes
  - concomitant increase in component depth and interaction complexity
  - concomitant observations of “phase transitions”, whereby component fail to meet the demands of higher scale
- progressive increase in robustness, deployment, & reliability issues:
  - complex failure modes are emerging
  - limited node and network capacity imply nontrivial event loss
  - byzantine nodes
- simulations have been inadequate to validate solutions, experiments have been necessary

# Kansei Testbed at Ohio State

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- Testbed to be located in a 5800 square foot warehouse near the Ohio State campus, leased for us by OSU's College of Engineering
- Comprises a hierarchy of sensor node platforms:
  - Tier 0: "dumb" sensors, actuators, DAC modules
  - Tier 1: smart dust sensor nodes (200)
  - Tier 2: StarGate sensor nodes (200)
  - Tier 3: pursuer and evader robots (planned)
  - Tier 4: application servers (PCs) running .Net (3)

# Testbed components

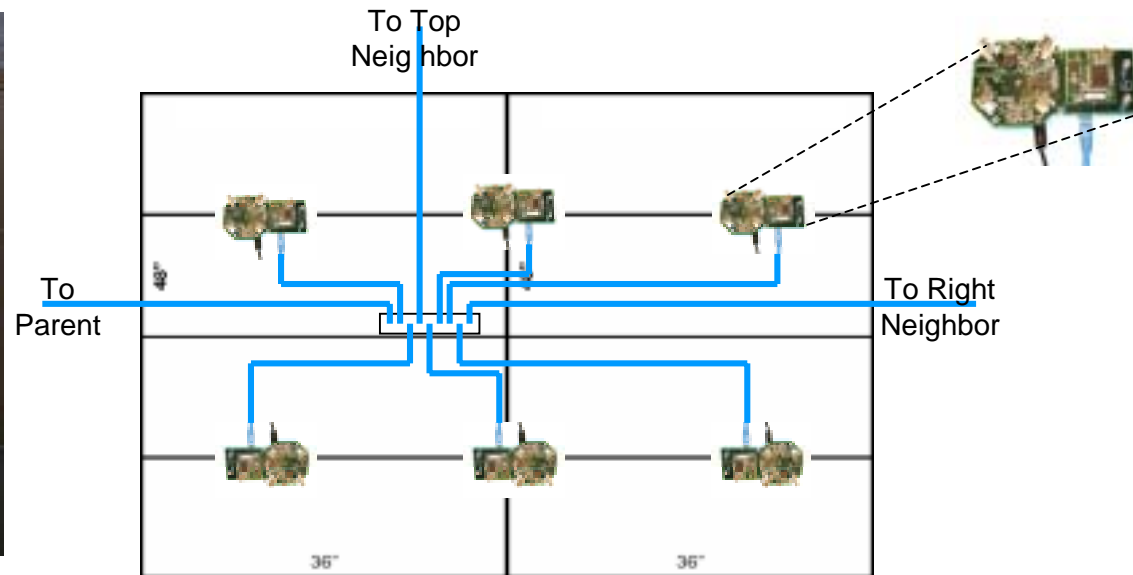
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- Tier 0:
  - Sensors: CO<sub>2</sub>, dissolved O<sub>2</sub>, light, pH, relative humidity, temperature, conductivity, mold
  - Actuators: water heaters, pumps, emitters, bubblers, portable heaters, ultrasonic humidifiers, CO<sub>2</sub> generators
- Tiers 1 and 2:
  - Sensors: photocell, PIR, MIR, temperature, magnetometer, microphone, GPS
  - Actuators: buzzers



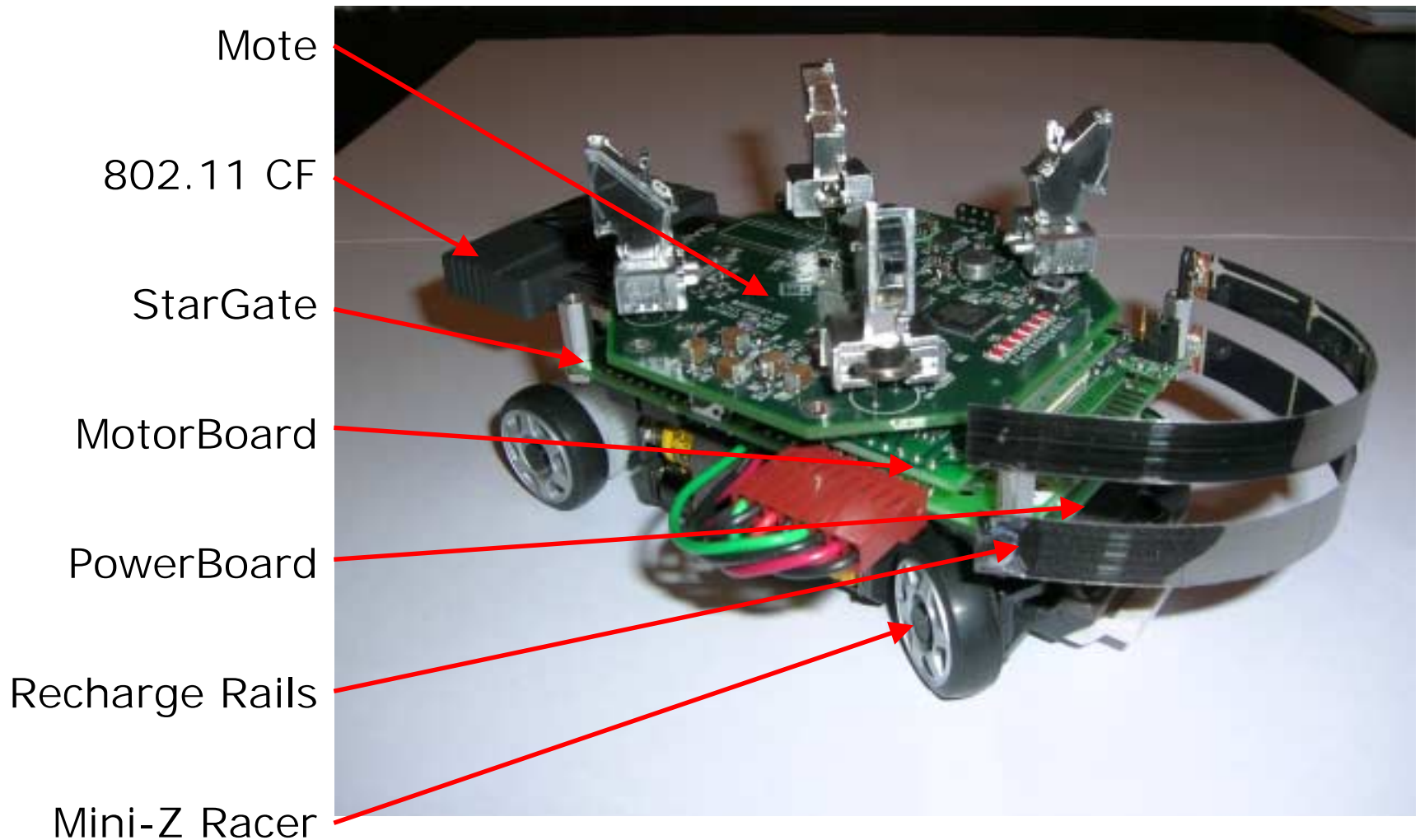
# Tier 1 & 2 nodes will be on an off-floor deck

- For physical reconfiguration, nodes partitioned into modules
  - abutted to form various desired planar topologies



- Nodes powered & out-of-band monitored using Ethernet

# Tier 1 & 2 nodes will eventually be mobile: Mote-on-Wheels



Tier 3 robots will be on the second deck

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## Some other testbed features

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- Remote instantiation of experiments
- Hybrid simulation and experimentation:
  - can drive experiments through field-recorded sensor stimulus
- Recording and playback of results through out-of-band network