

EE 816 - Lecture 16

1. Plane parallel problem: discretized angles solution
2. RT equations
3. Possible phase functions
4. Gaussian quadrature

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II. RT equations: plane parallel medium

Start again with

$$\frac{dI(\bar{r}, \hat{s})}{ds} = -\rho\sigma_t I(\bar{r}, \hat{s}) + \frac{\rho\sigma_t}{4\pi} \int_{4\pi} d\omega' p(\hat{s}, \hat{s}') I(\bar{r}, \hat{s}')$$

but consider only normal incidence (no azimuth dependency) and neglect polarization effects; also separate into reduced incident and diffuse components as

$$\begin{aligned} I_{ri}(\tau, \mu) &= F_0 e^{-\tau} \delta(\mu - 1) \delta(\phi) & (1) \\ \mu \frac{dI_d(\tau, \mu)}{d\tau} &= -I_d(\tau, \mu) + \frac{1}{4\pi} \int_{-1}^1 d\mu' \int_0^{2\pi} d\phi' p(\mu, \phi, \mu', \phi') I_d(\tau, \mu') \\ &\quad + \frac{p(\mu, \phi, 1, 0)}{4\pi} F_0 e^{-\tau} \end{aligned}$$

where $\mu = \cos\theta$ and we have assumed a normally incident plane wave

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I. Discretized angles solution

- We have now studied the first order iterative solution for a plane parallel medium
- However it is limited to the tenuous medium case, i.e. small scattering effects
- RT theory itself is not limited to this case; try to find a better solution
- Our next solution method discretizes the scattering integral into a sum; resulting equation can be solved using eigenvalue techniques
- The discretization is done using Gaussian quadrature; standard method for approximating an integral, analogous to Simpson's rule but more accurate
- Essentially a numerical solution of the RT equation, but some analytical forms can still be obtained and studied for a small number of points in the quadrature

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Note since for normal incidence I is independent of ϕ we can go ahead and perform the integrals over ϕ' . Also we can integrate the entire equation over ϕ to obtain:

$$\mu \frac{dI_d(\tau, \mu)}{d\tau} = -I_d(\tau, \mu) + \frac{1}{2} \int_{-1}^1 d\mu' p_0(\mu, \mu') I_d(\tau, \mu') + \frac{p_0(\mu, 1)}{4\pi} F_0 e^{-\tau}$$

where

$$p_0(\mu, \mu') = \frac{1}{2\pi} \int_0^{2\pi} d\phi \frac{1}{2\pi} \int_0^{2\pi} d\phi' p(\mu, \phi, \mu', \phi') \quad (2)$$

Also the boundary conditions in this problem remain

$$I_d(0, \mu) = 0 \quad 0 \leq \mu \leq 1 \quad (3)$$

$$I_d(\tau_0, \mu) = 0 \quad -1 \leq \mu \leq 0 \quad (4)$$

neglecting reflections at any boundaries

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III. Possible phase functions

- Before getting into the numerical solution for I_d Ishimaru reviews some typical phase functions and their properties
- Common choices:
 - Isotropic: $p_0(\mu, \mu') = \frac{\sigma_s}{\sigma_t} = W_0$
 - Rayleigh: $p_0(\mu, \mu') = \frac{3}{4} [1 + \mu^2 \mu'^2 + \frac{1}{2}(1 - \mu^2)(1 - \mu'^2)]$
 - General: expand in terms of Legendre polynomials
- Note these are already integrated over ϕ and ϕ'
- All of these functions turn out to have some symmetry properties that will be useful later on:

$$p_0(\mu, \mu') = p_0(\mu', \mu) = p_0(-\mu, -\mu') = p_0(-\mu', -\mu) \quad (5)$$

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Ishimaru reviews the basic ideas of Gaussian quadrature: begin by writing

$$\int_a^b f(x) dx \approx \sum_{j=1}^m a_j f(x_j) \quad (8)$$

here we are not going to necessarily choose x_j as evenly spaced points however.

Use the Lagrange interpolation formula to approximate $f(x)$:

$$f(x) = \sum_{j=1}^m f(x_j) \frac{F(x)}{(x - x_j)F'(x_j)} \quad (9)$$

where $F(x) = (x - x_1)(x - x_2)\dots(x - x_m)$, and the x_i 's are some set of abscissas.

The above equation is exact if $f(x)$ is a polynomial of degree $m - 1$ but only approximate otherwise. The equation works because it turns out that $\frac{F(x_i)}{(x_i - x_j)F'(x_j)}$ is 1 for $x_i = x_j$ but zero if $x_i \neq x_j$

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IV. Gaussian quadrature

- The basic idea of the numerical solution is to discretize the scattering integral in the RT equation:

$$\frac{1}{2} \int_{-1}^1 d\mu' p_0(\mu, \mu') I_d(\tau, \mu') \quad (6)$$

into a sum

$$\frac{1}{2} \int_{-1}^1 d\mu' p_0(\mu, \mu') I_d(\tau, \mu') \approx \frac{1}{2} \sum_{j=-N}^N a_j p_0(\mu, \mu_j) I_d(\tau, \mu_j) \quad (7)$$

- If this can be done, and we consider only discrete angles, the RT equation becomes an eigenvalue equation
- Gaussian quadrature is a method for approximating an integral with a sum; other methods could also be used but Gaussian quadrature is typically a very accurate method
- Discretizing the integral in the RT equation means we are using discrete values of *angle*; we still have continuous functions in z or τ

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Using this representation of $f(x)$ we can derive what the coefficients a_j should be in the approximation of the integral:

$$a_j = \frac{1}{F'(x_j)} \int_a^b \frac{F(x)}{(x - x_j)} dx \quad (10)$$

again which will provide an exact answer for the integral of a polynomial of degree $m - 1$

Our x_j 's are still arbitrary though; it turns out that if we choose them in a smart way we can obtain an exact answer for a polynomial of up to degree $2m - 1$!

The trick is to choose the x_j 's so that $F(x)$ becomes a Legendre polynomial which has the orthogonality properties we need. In the end we need $F(x) = P_m(x)$ and therefore the x_j 's are the zeros of the Legendre polynomial of order m

These are usually tabled for a given order m ; Ishimaru provides the cases with $m = 2$ and $m = 4$; numerical recipes has a routine for higher order

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- The integral we are interested in is

$$\frac{1}{2} \sum_{j=-N}^N a_j p_0(\mu, \mu_j) I_d(\tau, \mu_j) \quad (11)$$

- Therefore our μ_j 's will be the zeros of the Legendre Polynomial of order $2N$ (j defined to be both positive and negative)
- This choice is useful because the a_j 's and μ_j 's have some symmetries: $a_j = a_{-j}$ and $\mu_j = -\mu_{-j}$
- In other words we evaluate the function at both positive and negative values with the same weights when calculating the integral
- Since $\mu = \cos\theta$, μ_j we will choose to be positive and therefore represents a forward going wave; μ_{-j} is backward going
- We will define the largest positive value to be μ_N , therefore the most negative value is μ_{-N} . μ_N is therefore the closest to 0 degrees, others rotate backwards

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I. Discretized angle solution

We have now discretized the integral in the RT equation to obtain

$$\mu \frac{dI_d(\tau, \mu)}{d\tau} = -I_d(\tau, \mu) + \frac{1}{2} \sum_{j=-N}^N a_j p_0(\mu, \mu_j) I_d(\tau, \mu_j) + \frac{p_0(\mu, 1)}{4\pi} F_0 e^{-\tau}$$

Now let's evaluate this equation at $\mu = \mu_i$ (same values as μ_j 's):

$$\mu_i \frac{dI_d(\tau, \mu_i)}{d\tau} = -I_d(\tau, \mu_i) + \frac{1}{2} \sum_{j=-N}^N a_j p_0(\mu_i, \mu_j) I_d(\tau, \mu_j) + \frac{p_0(\mu_i, 1)}{4\pi} F_0 e^{-\tau}$$

which can be re-written as a matrix equation in terms of $I_d(\tau, \mu_i)$:

$$\frac{d\bar{I}_d(\tau)}{d\tau} + \bar{S} \cdot \bar{I}_d(\tau) = \bar{B} e^{-\tau} \quad (12)$$

This is a standard system of first order differential equations.

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1. Discretized angle solution of RT equation
2. Homogeneous solution
3. Matching boundary conditions and final answer
4. Example with $N = 1$

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- We arrange $\bar{I}_d(\tau)$ as $[I_d(\tau, \mu_i)]$ with $i = (+N, \dots, +1, -1, \dots, -N)$
- The \bar{S} matrix contains both the extinction term $-I_d(\tau, \mu_i)$ and the scattering terms $\frac{1}{2} \sum_{j=-N}^N a_j p_0(\mu_i, \mu_j) I_d(\tau, \mu_j)$
- The right hand side contains the incident field source term $\frac{p_0(\mu_i, 1)}{4\pi} F_0 e^{-\tau}$
- Ishimaru describes these components in detail; the \bar{S} matrix has several symmetry properties due to properties of p_0
- However, \bar{S} is not symmetric
- Solving a system of first order diff. eqn's requires a particular and homogeneous solution
- Guessing a particular solution is easy: plug in $\bar{I}_p(\tau) = \bar{\alpha} e^{-\tau}$ and solve for the constant vector $\bar{\alpha} = (\bar{S} - \bar{U})^{-1} \cdot \bar{B}$ where \bar{U} is the identity matrix

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II. Homogeneous solution

- As with any first order DE we must also include a homogeneous (or “complementary”) solution with unknown constants in order to match the boundary conditions
- In this case the homogeneous solution satisfies

$$\frac{d\bar{I}_c(\tau)}{d\tau} + \bar{S} \cdot \bar{I}_c(\tau) = 0 \quad (13)$$

- If we look for solutions of the form:

$$\bar{I}_c(\tau) = \bar{\beta} e^{\lambda\tau} \quad (14)$$

we obtain the equation

$$\left(\lambda\bar{I} + \bar{S}\right) \cdot \bar{\beta} = 0 \quad (15)$$

- For a non-trivial solution the determinant of the matrix must vanish: exactly an eigenvalue problem!

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III. Matching BC’s and final answer

- Next the boundary conditions:

$$I_d(0, \mu_i) = 0 \quad 0 \leq \mu_i \leq 1 \quad (19)$$

$$I_d(\tau_0, \mu_i) = 0 \quad -1 \leq \mu_i \leq 0 \quad (20)$$

are applied to determine the unknown constants

- Writing these equations produces a system of linear equations in C_n which is solved by matrix inversion. Size of matrix = $2N$
- Once the constants are found we know $I(\tau, \mu_i)$ everywhere inside our layer; however it is discretized in angle
- Ishimaru converts back into a continuous function of angle using the RT integral equation; this integrates over angle and gets rid of discretization
- On page 211-212 Ishimaru presents the final continuous solution in terms of $\bar{\alpha}$, sums over the constants C_n , the eigenvalues λ_n and the eigenvectors $\bar{\beta}_n$

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- The determinant equation will produce a polynomial in λ of order $2N$; therefore we find $2N$ eigenvalues λ_n ; corresponding to each is an eigenvector $\bar{\beta}_n$ which contains $2N$ elements
- Ishimaru tells us that there are actually positive and negative pairs of eigenvalues $\lambda_n = -\lambda_{-n}$ whose eigenvectors are related also
- Our complementary solution is therefore written as a sum over all the eigenfunctions with unknown coefficients:

$$\bar{I}_c(\tau) = \sum_{n=1}^N C_n \bar{\beta}_n e^{\lambda_n \tau} + \sum_{n=1}^N C_{-n} \bar{\beta}_{-n} e^{-\lambda_n \tau} \quad (16)$$

- Our complete solution is thus

$$\bar{I}_d(\tau) = \bar{I}_p(\tau) + \bar{I}_c(\tau) \quad (17)$$

$$= \bar{\alpha} e^{-\tau} + \sum_{n=1}^N C_n \bar{\beta}_n e^{\lambda_n \tau} + \sum_{n=1}^N C_{-n} \bar{\beta}_{-n} e^{-\lambda_n \tau} \quad (18)$$

- Discrete functions of μ but continuous functions of τ !

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IV. $N = 1$ example

- Ishimaru illustrates the whole procedure on page 213-215 for isotropic scattering and using $N = 1$
- Since with $N = 1$ there are only two angles to consider he manages to compute things analytically; larger N 's would require a computer however
- Particular solution, eigenvalues, eigenvectors all found and expressed in terms of albedo W_0
- System of equations to determine the C_n 's is also simple since it is only 2 by 2; larger N 's require matrix inversion routines
- Final analytical answer is interesting; shows additional terms beyond first order iterative solution
- However, care must be exercised in using this solution since it was based only on $N = 1$; larger values of N should give better answers but would not be easy to write analytically

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Review of procedure:

- Choose an order of quadrature N ; look up values of a_j 's and μ_j 's
- Compute phase matrix using $p_0(\mu_i, \mu_j)$, this will be a $2N$ by $2N$ matrix
- Construct the $\overline{\overline{S}}$ matrix from phase matrix and extinction term as given in book; should have correct symmetry properties
- Construct the right hand side vector \overline{B} as specified in book
- Determine particular solution $\overline{I}_p(\tau) = \overline{\alpha}e^{-\tau}$ through

$$\overline{\alpha} = (\overline{\overline{S}} - \overline{\overline{U}})^{-1} \cdot \overline{B} \quad (21)$$

- Determine complementary solution from eigenvalues and eigenvectors of the $\overline{\overline{S}}$ matrix; canned computer routines to do this

- NOTE: canned routines must be used carefully to make sure they solve the appropriate eigenproblem; also result probably needs rearranging to match Ishimaru's ordering scheme
- Construct the boundary condition matrix equation using eigenvalues and eigenvectors; invert to determine C_n 's
- Once this is completed, the solution for any value of τ or μ can be computed using Ishimaru's equations p. 211-212; requires a sum over N to do so
- To obtain backscattering, find $I_d(0, -1)$ (i.e. intensity at $\tau = 0$ going in $-z$ direction). A backscattering coefficient σ is found from 4π times this
- Note our method only works for normal incidence: for oblique incidence we have to worry about variations in ϕ . Can still be done as mentioned in 11 – 6 by decomposing things into azimuthal harmonics

